

## Problem Set 2

- This problem set is due on **March 15, 2021**.
- Each problem carries 10 points.
- Collaboration is **not permitted**. Each student must submit his/her own work.

1. **(Random Walk)** Let  $\{X_n\}_{n \geq 1}$  be a sequence of i.i.d. random variables with

$$\mathbb{P}(X_1 = 1) = p, \mathbb{P}(X_1 = -1) = 1 - p,$$

where  $0 \leq p \leq 1$  and  $p \neq \frac{1}{2}$ . Let  $S_0 = 0$  and  $S_n = S_{n-1} + X_n, n \geq 1$ . For each  $n \geq 1$ , define the event  $A_n = \{\omega : S_n(\omega) = 0\}$  and let  $A = \limsup A_n$ . Let  $\mathcal{F}_\infty$  be the tail  $\sigma$ -algebra corresponding to the sequence of r.v.s  $\{X_n\}_{n \geq 1}$ . Show that

- (a)  $A \notin \mathcal{F}_\infty$ .
- (b) Nonetheless,  $\mathbb{P}(A) \in \{0, 1\}$ .

† HINT: Use Stirling's approximation.

2. **(Conditional Expectation)**

- (a) Let the random variables  $\{Z_n\}_{n \geq 1}$  be independent, each with finite mean. Let  $X_0 = a$ , and  $X_n = a + Z_1 + Z_2 + \dots + Z_n$  for  $n \geq 1$ . Prove that

$$\mathbb{E}(X_{n+1} | \sigma(X_1, X_2, \dots, X_n)) = X_n + \mathbb{E}(Z_{n+1}).$$

- (b) Suppose that  $X, Y \in \mathcal{L}^2(\Omega, \mathcal{F}, \mathbb{P})$  such that

$$\mathbb{E}(X | \sigma(Y)) = Y, \mathbb{E}(Y | \sigma(X)) = X \quad \text{a.s.}$$

Show that  $X = Y$  almost surely.

- (c) **(Linear Estimation)** Let  $X_1, X_2, \dots, X_n$  be random variables with zero expectations and covariance matrix  $\mathbf{V}$ <sup>1</sup>. Using the orthogonality principle, find the linear map  $h(\cdot)$  of  $\{X_i\}_{i=1}^n$  which minimizes the mean squared error  $\mathbb{E}\{(Y - h(X_1, X_2, \dots, X_n))^2\}$ .

<sup>1</sup>This means that  $V_{ij} = \mathbb{E}(X_i X_j), 1 \leq i, j \leq n$ .

### 3. (Kolmogorov-Hajek-Renyi inequality)

(a) Show that if  $X$  is a non-negative supermartingale and  $T$  is a stopping time, then

$$\mathbb{E}(X_T; T < \infty) \leq \mathbb{E}(X_0).$$

Hence or otherwise, show that  $\mathbb{P}(\sup_n X_n \geq c) \leq \mathbb{E}(X_0)/c$ .

(b) Let  $\{Z_n\}_{n \geq 0}$  be a Martingale sequence with  $Z_0 = 0$  and let  $\{v_j\}_{j \geq 0}$  be a sequence of non-decreasing constants with  $v_0 = 0$ . Prove that

$$\mathbb{P}(|Z_j| \leq v_j, \forall 1 \leq j \leq n) \geq 1 - \sum_{j=1}^n \mathbb{E}(Z_j - Z_{j-1})^2 / v_j^2.$$

**Hint:** Define the stopping time  $N$  to be the first time for which  $|Z_N| > v_N$ . Let it be equal to  $n$  if  $|Z_j| \leq v_j, \forall 1 \leq j \leq n$ . Now analyze the corresponding stopped Martingale.

4. **(Randomized polynomial-time solvability of 2-SAT)** In this problem, we will analyze a simple randomized algorithm for 2-satisfiability.

(a) Consider a supermartingale  $\{X_t\}_{t \geq 1}$  that takes values in  $\{0, 1, 2, \dots, n\}$ , with  $X_0 = s$ . Set  $D_t := X_t - X_{t-1}, t \geq 1$  and assume that for all  $t \geq 1$  we have  $\mathbb{E}(D_{t+1}^2 | \mathcal{F}_t) \geq \sigma^2$ , for some constant  $\sigma^2$ . We are interested in  $T$ , the number of steps needed for  $X_t$  to reach 0. Show that

$$\mathbb{E}(T) \leq \frac{2ns - s^2}{\sigma^2} \leq \frac{n^2}{\sigma^2}.$$

(b) Recall the classic Boolean Satisfiability problem <sup>2</sup>. Show that the following simple randomized polynomial time algorithm will find a satisfying assignment (given that it exists) in expected quadratic time.

Given a 2-CNF formula  $\phi$  with  $n$  variables, pick an arbitrary initial assignment  $a_0$ . If  $\phi$  is not satisfied by  $a_0$ , pick an arbitrary unsatisfied clause  $C_0$ . Choose a literal of  $C_0$  uniformly at random and flip the value of that variable to obtain assignment  $a_1$ . Using the result of part (a), show that the algorithm will find a satisfying assignment (given that it exists) after at most  $O(n^2)$  rounds in expectation.

### 5. (Controlling a spaceship)

(a) Imagine that you are the captain of a spaceship currently located at a distance of  $R_0$  from the solar system. Your objective is to steer the spaceship into the solar system, which is assumed to be a ball of radius  $r < R_0$  centered around the Sun located at the origin. You can set the distance to be traveled by the space-ship in each hop based on the available information. However, due to some unfortunate mechanical failures, you can no longer specify the direction of movement. As

<sup>2</sup><https://www2.cs.duke.edu/courses/fall14/compsci330/notes/scribe23.pdf>

a result, at every hop, the spaceship moves in a direction chosen uniformly at random over a 3D sphere of a radius of your choice from its previous location. Let  $R_n$  be the distance from the Sun to your spaceship after  $n$  hops. Show that irrespective of the control strategy adopted, the sequence  $\{\frac{1}{R_n}\}_{n \geq 1}$  is a supermartingale and that for any strategy which always sets a distance no greater than that from Sun to your spaceship,  $\{\frac{1}{R_n}\}_{n \geq 1}$  constitutes a Martingale sequence. Hence or otherwise, show that

$$\mathbb{P}[\text{The spaceship enters into the solar system}] \leq r/R_0.$$

**Hint:** You may need to use a classic result from high-school physics on the gravitational potential of a uniform spherical shell to evaluate an integral appearing in this problem.

- (b) Assume that after working on the faulty engine for hours, you have been able to confine the random motion of the spaceship along a fixed plane passing through the Sun. However, the next hop-length is now automatically set to the current distance to the Sun. In other words, if the distance to the Sun from the spaceship after the  $n^{\text{th}}$  hop is  $R_n$ , in the next hop, the spaceship is moved uniformly at random on a circle with center at the current location and radius  $R_n$ . Show that the spaceship gets into the solar system almost surely.

**Hint:** Define the r.v.s  $V_n = \ln R_n - \ln R_{n-1}$ ,  $n \geq 1$ . Show that  $\{V_n\}_{n \geq 1}$  are i.i.d. with zero mean and non-zero but finite variance. Now consider the summation  $S_n = \sum_{k=1}^n V_k$ . Using CLT, show that  $\mathbb{P}(\inf_n S_n < \ln(r_0/R_0)) = 1$  and conclude the result.